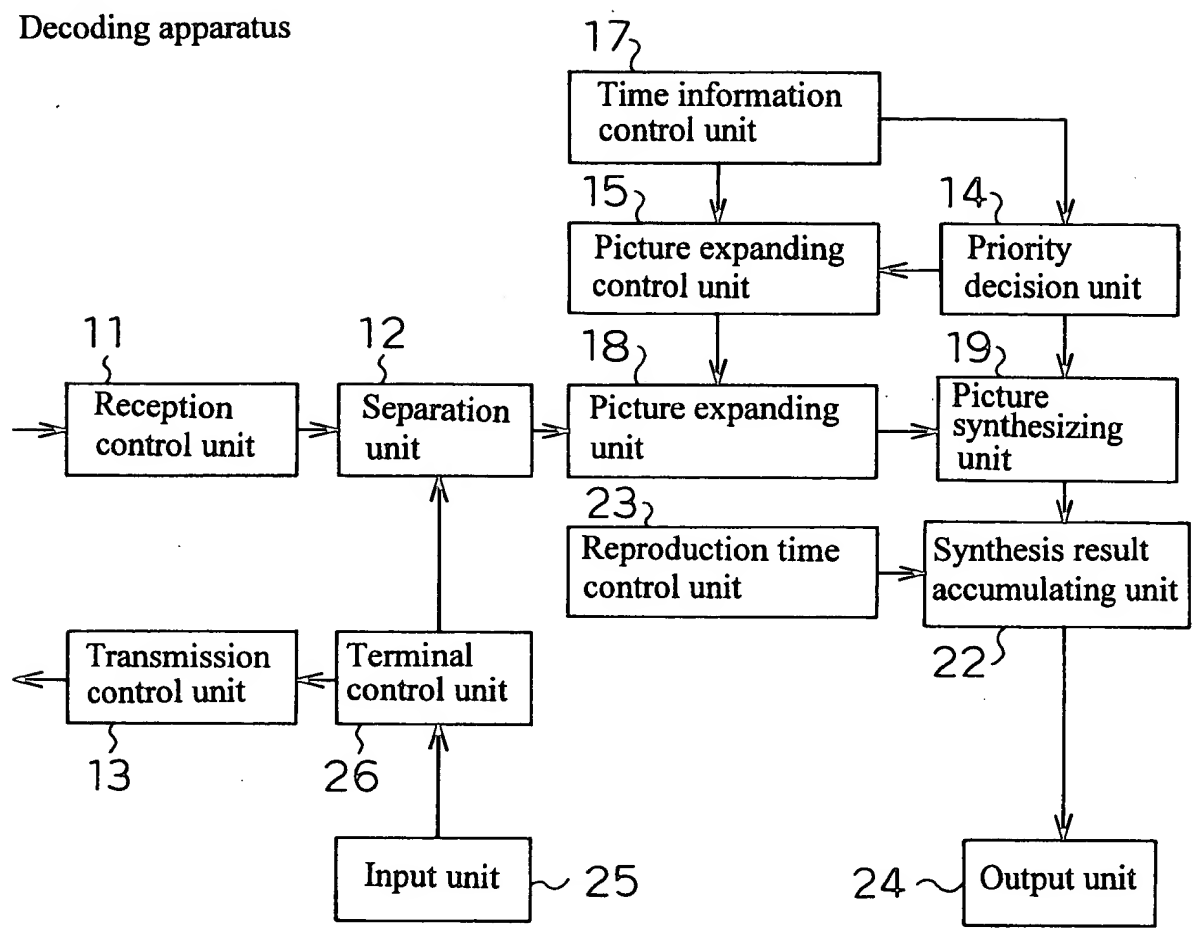
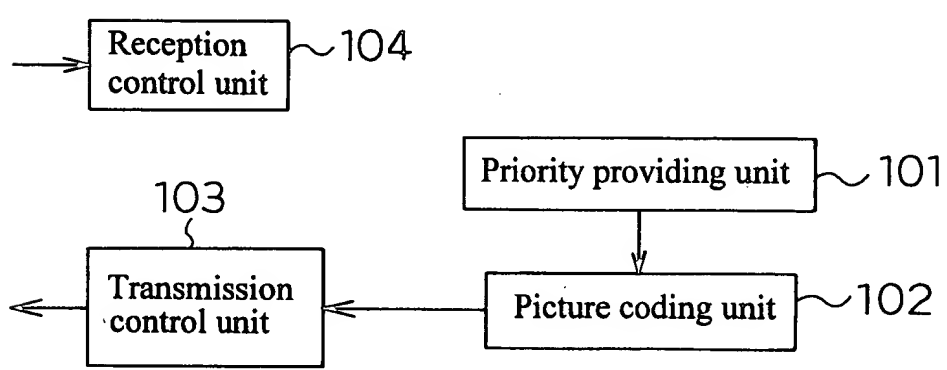


Fig. 1

Decoding apparatus



Coding apparatus

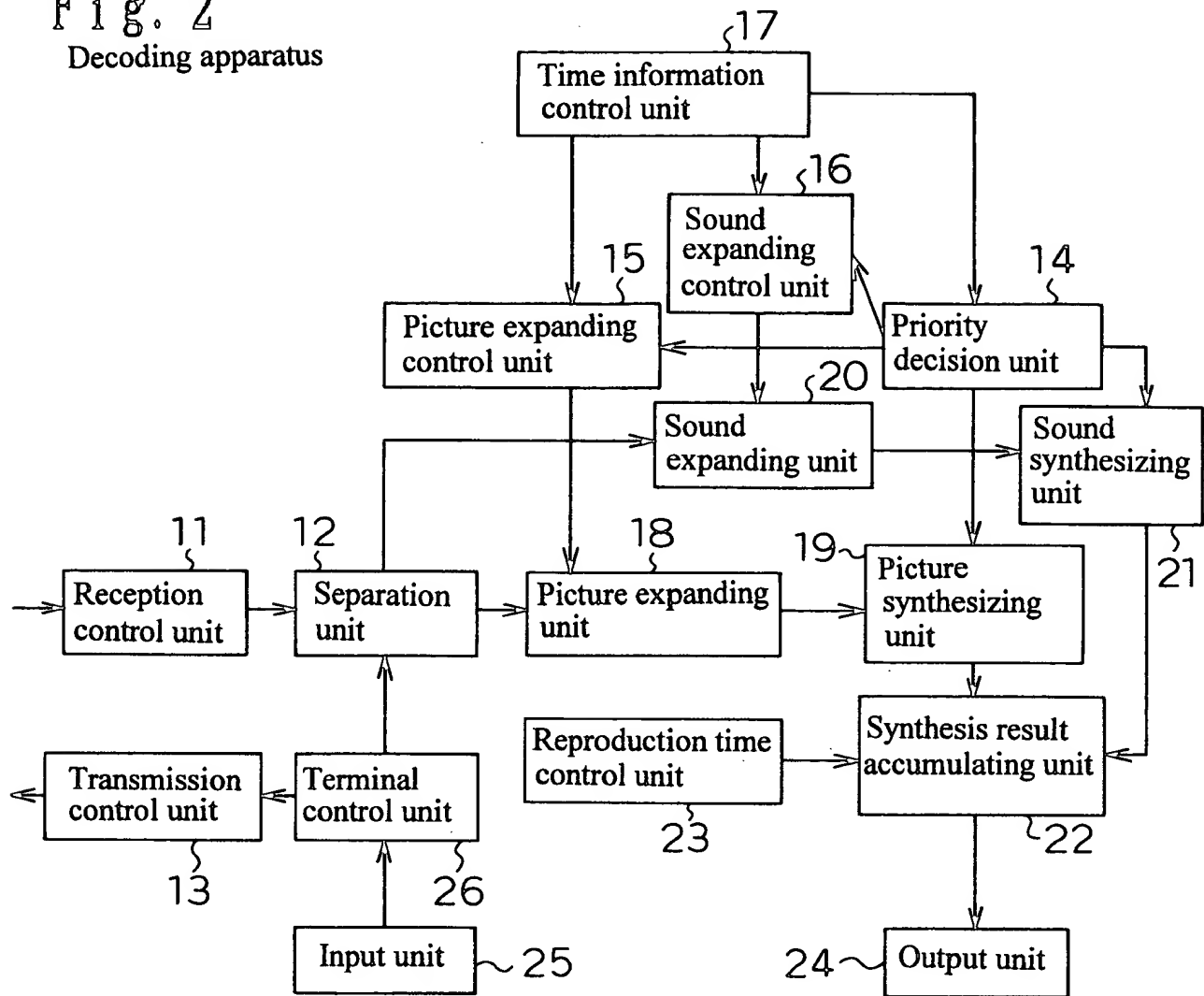


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Fig. 2

Decoding apparatus



Coding apparatus

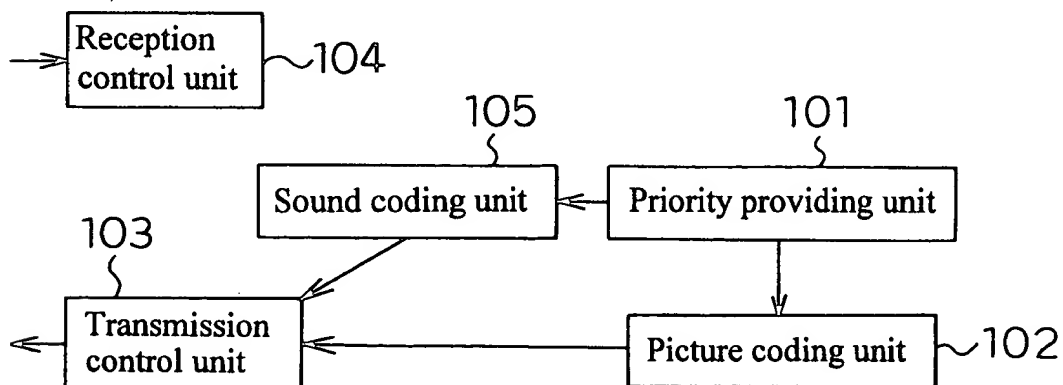


Fig. 3 (a)

All multiplexed format

Header information	Priority for defining reproduction sequence	Priority for defining processing when overloaded	Picture data 1	Sound data 1	-----	Picture data N	Sound data N
--------------------	---	--	----------------	--------------	-------	----------------	--------------

Information showing display sequence

* The information describing the relation between pictures or between sounds may be described in the header information.

Fig. 3 (b)

Multiplexed in individual media, and transmitted from respective communication ports

Header information	Priority for defining reproduction sequence	Priority for defining processing when overloaded
--------------------	---	--

Control information

Header information	Picture data 1	-----	Picture data N
--------------------	----------------	-------	----------------

Picture data row

Header information	Sound data 1	-----	Sound data N
--------------------	--------------	-------	--------------

Sound data row

Semaphore

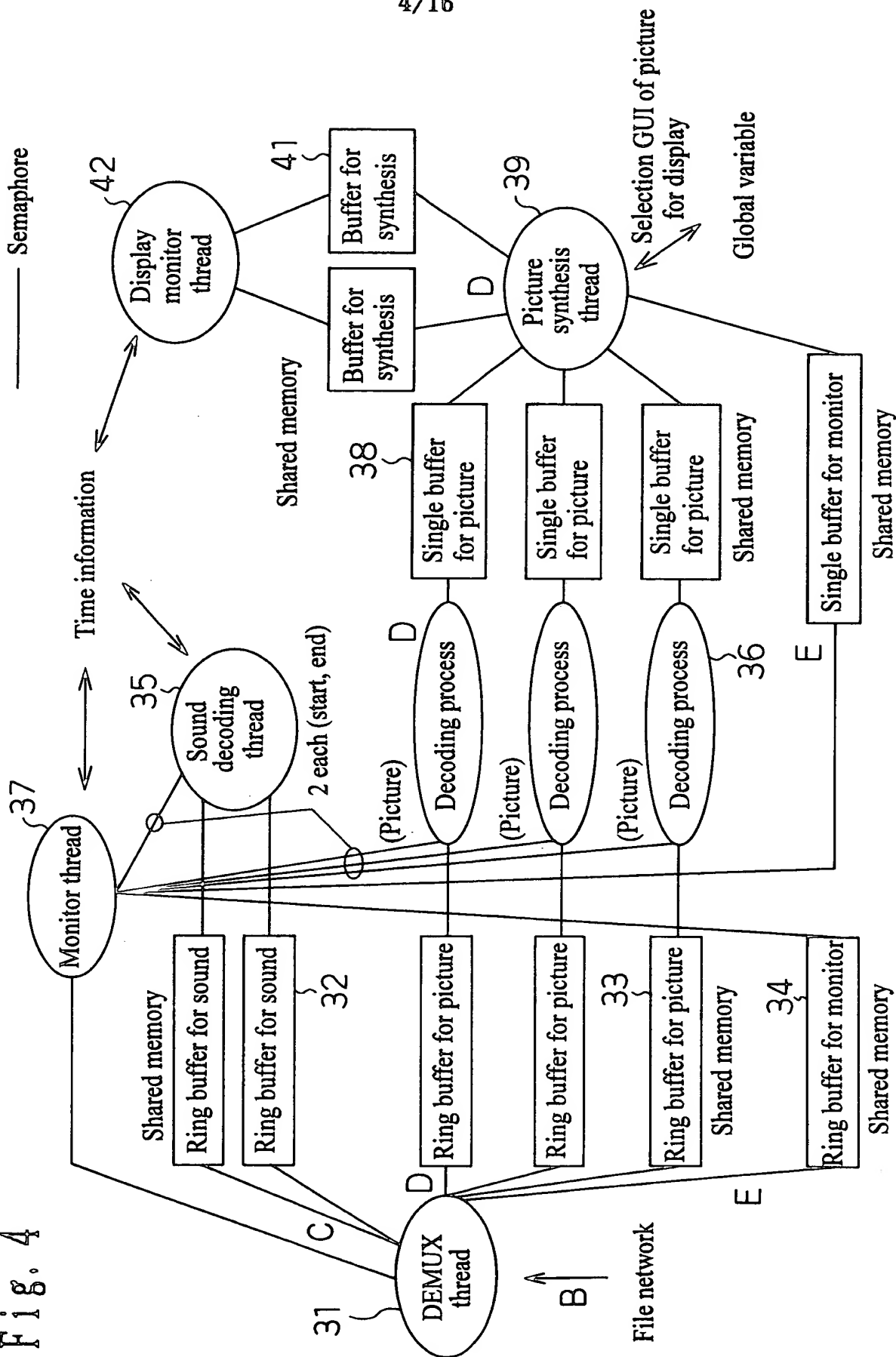


Fig. 5

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B.

```

struct shm_tspkt {
    data_byte      188byte      Packet data
}

```

C.

```

struct shm_apkt {
    DWORD  sync_code      32bit  Packet synchronous code
    WORD   pts            16bit  Display time
    WORD   frame_length   16bit  Frame length
    BYTE   data_byte      Nbyte  Sound data
                                (N=frame_length)
}

```

D.

```

struct shm_vpkt {
    DWORD  sync_code      32bit  Packet synchronous code
    BYTE   temporal_reference 8bit  Frame number
    WORD   frame_length   16bit  Frame length
    BYTE   data_byte      Nbyte  Picture data
                                (N=frame_length)
}

```

E.

```

struct shm_kanshi_info {
    WORD  pts            16bit  Display time
    BYTE  number_of_object 8bit  No. of objects
    for (i=0: i<number_of_object:i++) {
        BYTE  object_id      8bit  ID
        BYTE  temporal_reference 8bit  Frame number
        BYTE  object_priority 4bit  Priority (*1)
        reserved      2bit
        IPB_flag      2bit  Frame type
        WORD  horizontal_offset 10bit  Display position, horizontal
        WORD  vertical_offset  10bit  Display position, vertical
        BYTE  layer            4bit  Layer
    }
}

```

(*1) Bits are assigned from the highest position sequentially by 4 bits (object_priority), 2 bits, 2 bits (IPB_flag)

Fig. 6

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DEMUX thread

```

void demux ( )
{
    Shared memory (ring), semaphore generation process: for output
        (2 for sound, 3 for picture, 1 for monitor table)
    Semaphore generation for monitor thread control (one)
    BOOL flag = TRUE: // State of ring buffer

    while(1) {
        if(flag) Reading from file or network - (5-1)

        if(flag)
            Analysis of 188-byte packet data, setting in specified structure - (5-2)
            (decomposed into information of sound, picture, monitor table)

        // Exclusive control of ring buffer by semaphore
        if (Able to write in ring buffer?) {
            Write into ring buffer (from earlier object ID, write sequentially - (5-3)
                into shared memory of earlier buffer number)
            Advance write pointer of written buffer - (5-4)
            flag=TRUE:
        }else
            flag=FALSE: // Prevent overflow of ring buffer

        if(flag)
            After writing information of pictures and sounds for one monitor - (5-5)
            table, advance the counter of semaphore for monitor thread control
    }
}

```

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Fig. 7

Monitor thread

```
void Watch Process ( )
{
```

```
    BYTE disp_TR[i]: // Picture serial number (shared memory)
    BOOL skip_flag[i]: // Skip flag to which decoding process refers
                        (shared memory)
```

```
    Shared memory (ring buffer: monitor table 1)
```

```
        Semaphore open: used by determining priority of processing
```

```
    Shared memory (single buffer: monitor table 1)
```

```
        Semaphore generation: transfer to synthesis side
```

```
    Generation of semaphore for process monitor
```

```
    Semaphore open for monitor thread control (one)
```

```
    Start of picture decoding process
```

```
    Confirm start of process
```

```
    while {skip_flag[i]=FALSE: // Not skipped }
```

```
    while(1)
```

```
    {
```

```
        Reading of monitor table (read pointer update, from DEMUX)
```

```
        Check of object priority
```

```
        - (6-1) - (6-2)
```

```
        Writing of monitor table (to synthesis side)
```

```
        - (6-3)
```

```
        Wait for creation of data for one monitor table from DEMUX
```

```
        - (6-4)
```

```
        From highest priority
```

```
        {
```

```
            disp_TR[i]=TR:
```

```
            - (6-5)
```

```
            if ( Present time > display time (pts) ) {
```

```
            - (6-6)
```

```
                Not skipped if I frame
```

```
                skip_flag[i]=FALSE
```

```
            }else{
```

```
                P, B frames are skipped
```

```
                skip_flag[i]=TRUE
```

```
            }
```

```
        Release of semaphore of corresponding process
```

```
        - (6-7)
```

```
        Wait for release of semaphore of corresponding process
```

```
        - (6-8)
```

```
        (process completion check)
```

```
    }
```

```
    }
```

```
}
```

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Fig. 8

Decoding process

```
void main(int argc, char *argv[ ] )  
{
```

Value received from main process :
Shared memory to be opened, name of semaphore

Shared memory (ring), open processing of semaphore: for input (from MUX)
Shared memory (single), open processing of semaphore: for output (to synthesis side)

```
while(1) {  
    Monitor thread waits for release of semaphore - (7-1)  
  
    Input picture state check: - (7-2)  
        Picture serial number (TR), skip input frame?  
  
    Wait for picture data to be decoded - (7-3)  
  
    Is TR present in shared memory? { - (7-4)  
        Skip decoding if not present  
        Advance read pointer for ring buffer (for input)  
    }  
  
    if (Skip one input frame) {  
        Decoding process - (7-5)  
        Advance read pointer for ring buffer (for input)  
    }  
  
    Output of decoding result (*1) - (7-6)  
    Release semaphore to monitor thread (process end notice) - (7-7)  
}
```

(*1) When skipping input frame process, send signal to main process without decoding process and output of decoding result

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```
void Watch Sync ( )
{
```

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Fig. 10

Display monitor thread

```

void Watch Disp ( )
{
    Shared memory (single), open processing of semaphore: for input
                                                (from synthesis thread: 2)
    BOOL  flag = TRUE:

    while(1)
    {
        // Double buffer
        if (flag) {
            Wait for synthesis picture from shared memory (from synthesis thread)#1
            flag = FALSE:                                     - (9-1)
        } else {
            Wait for synthesis picture from shared memory (from synthesis thread)#2
            flag = TRUE:
        }

        if (Initial display) {
            Acquire display start time from timer                                     - (9-2)
        }
        Sleep (pts-nowtime):                                     - (9-3)
        Display of synthesis picture
    }
}

```

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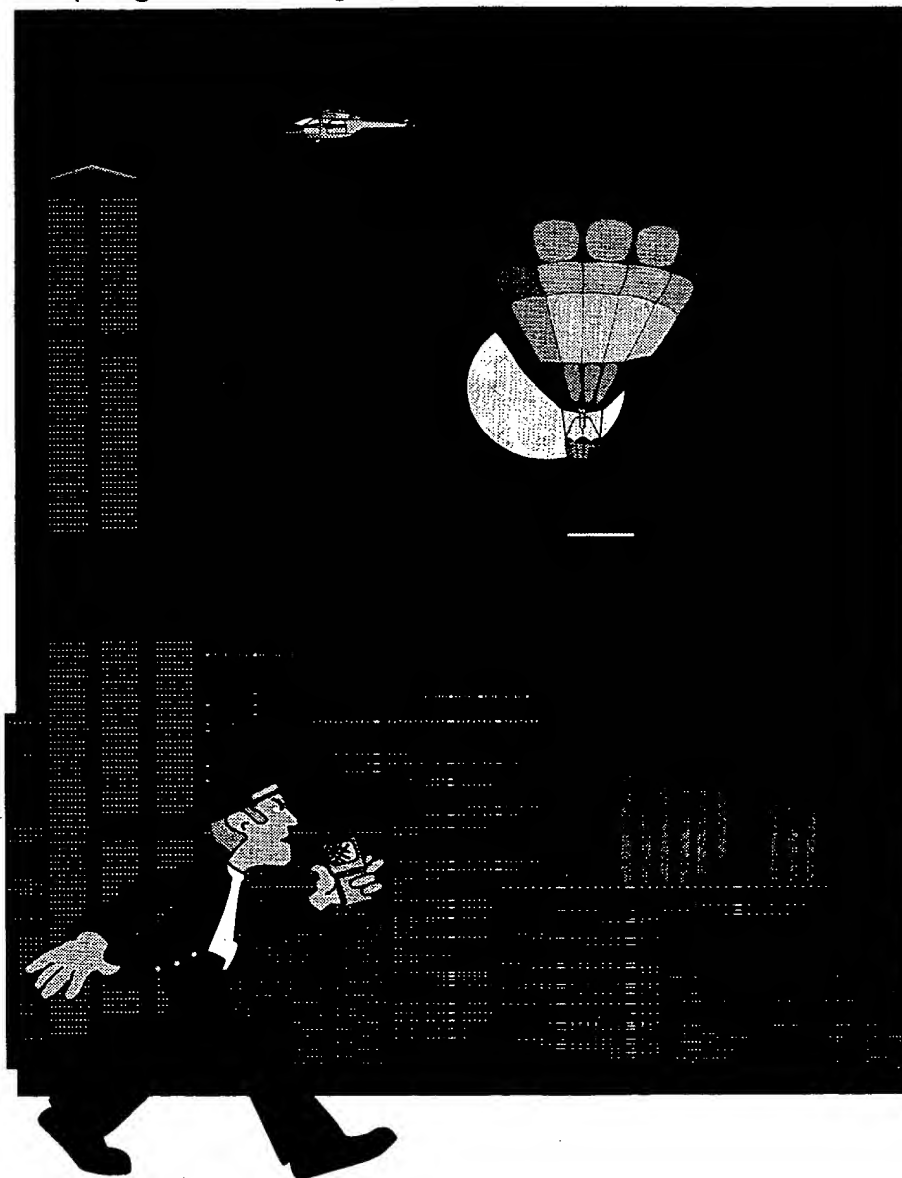
Fig. 11

Three-dimensional picture
(foreground: helicopter)

Three-dimensional picture
(foreground: balloon)

Background picture
(night sky)

Foreground picture
(building)
Synthesis ratio: 0.5



Foreground picture (man)

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Fig. 12 (a)

System of hardware base

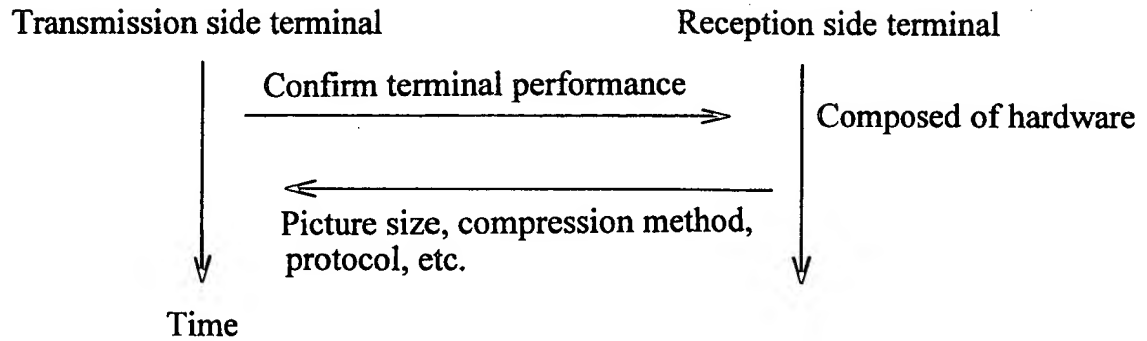
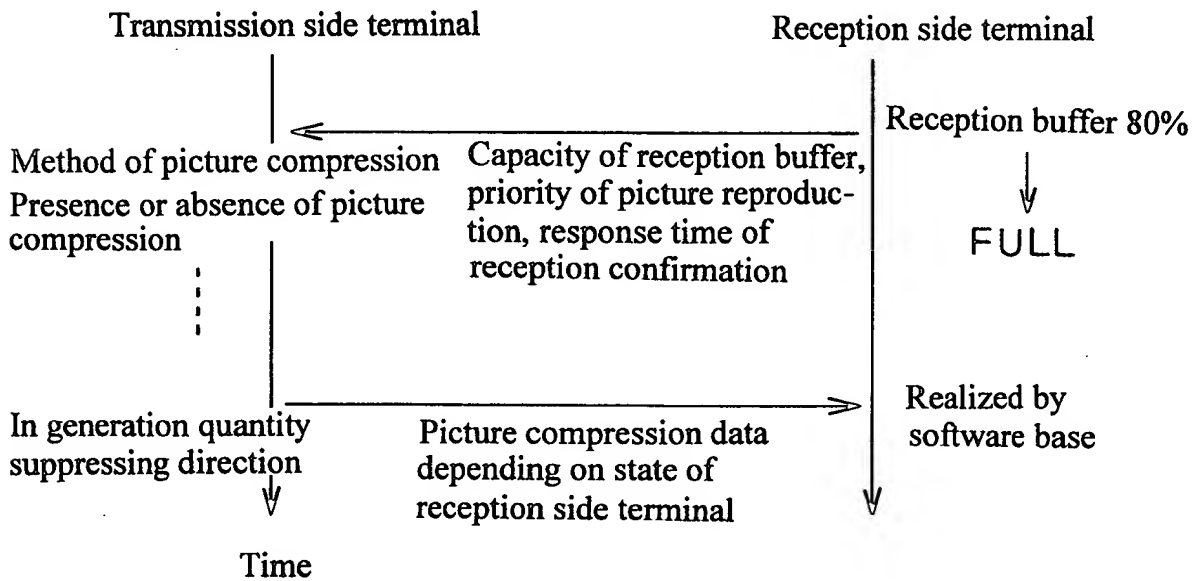


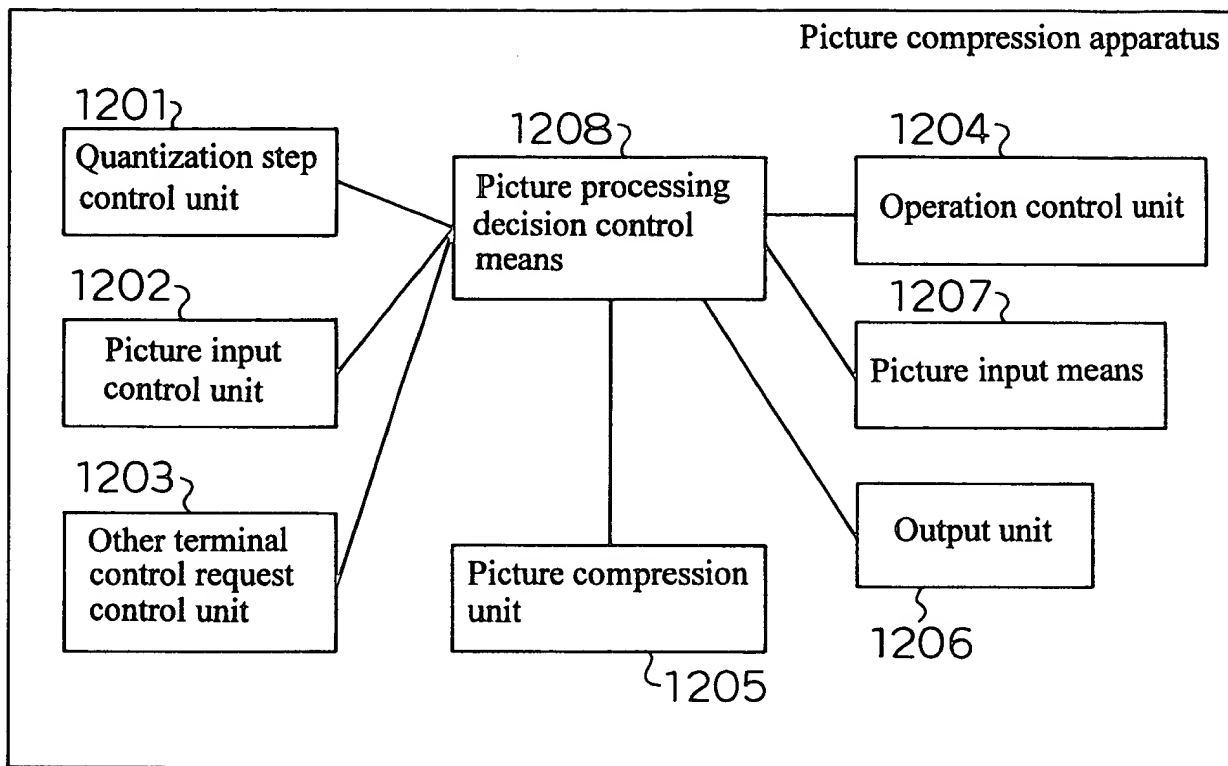
Fig. 12 (b)

System of software base



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Fig. 13



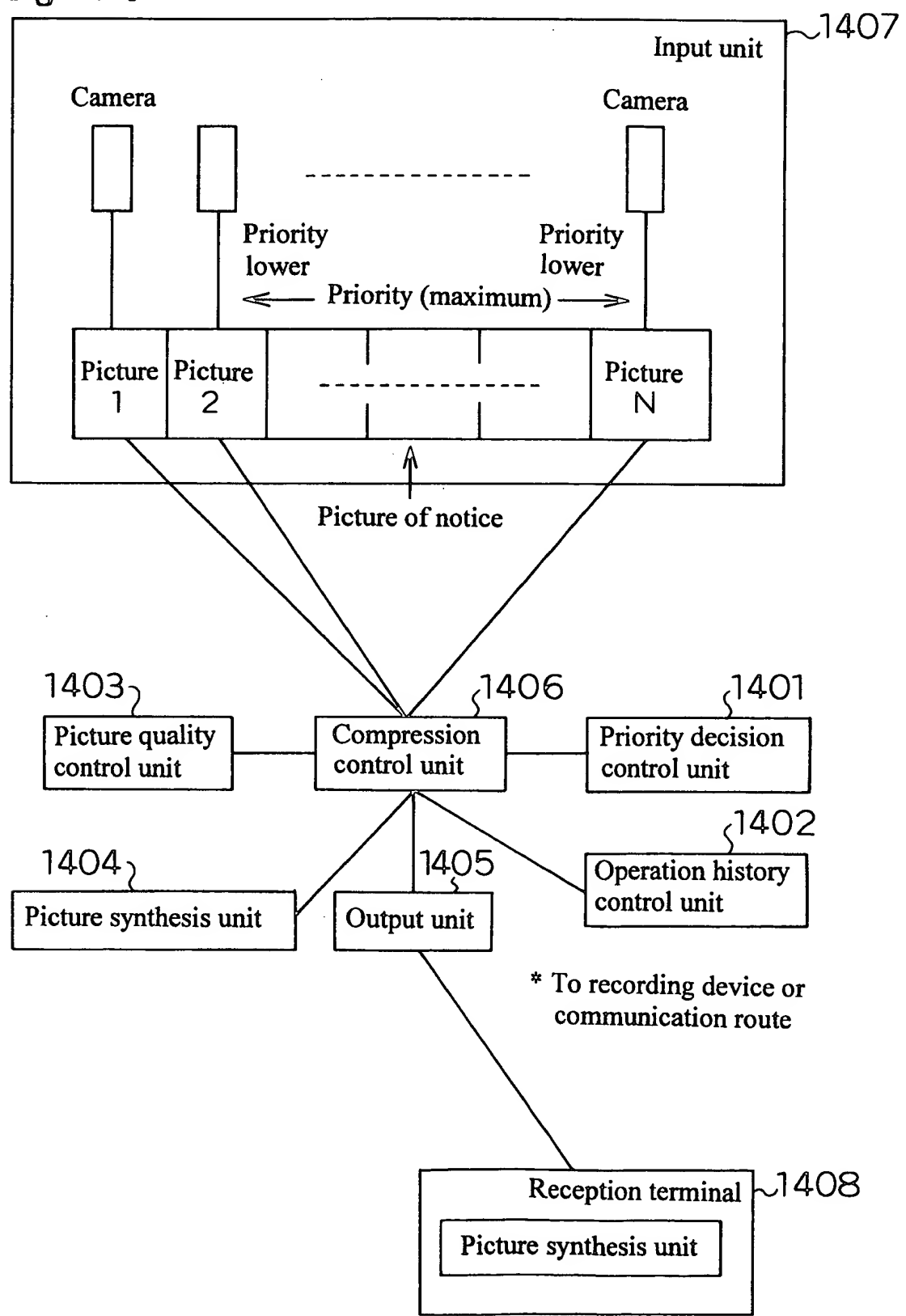
* Sound compression apparatus can be set similarly

Fig. 14

Picture size	Camera control	Other terminal control request	Quantization step
QC I F	Pan	Buffer over	16
C I F	None	None	16
QC I F	None	None	18
QC I F	Tilt	None	14

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Fig. 15

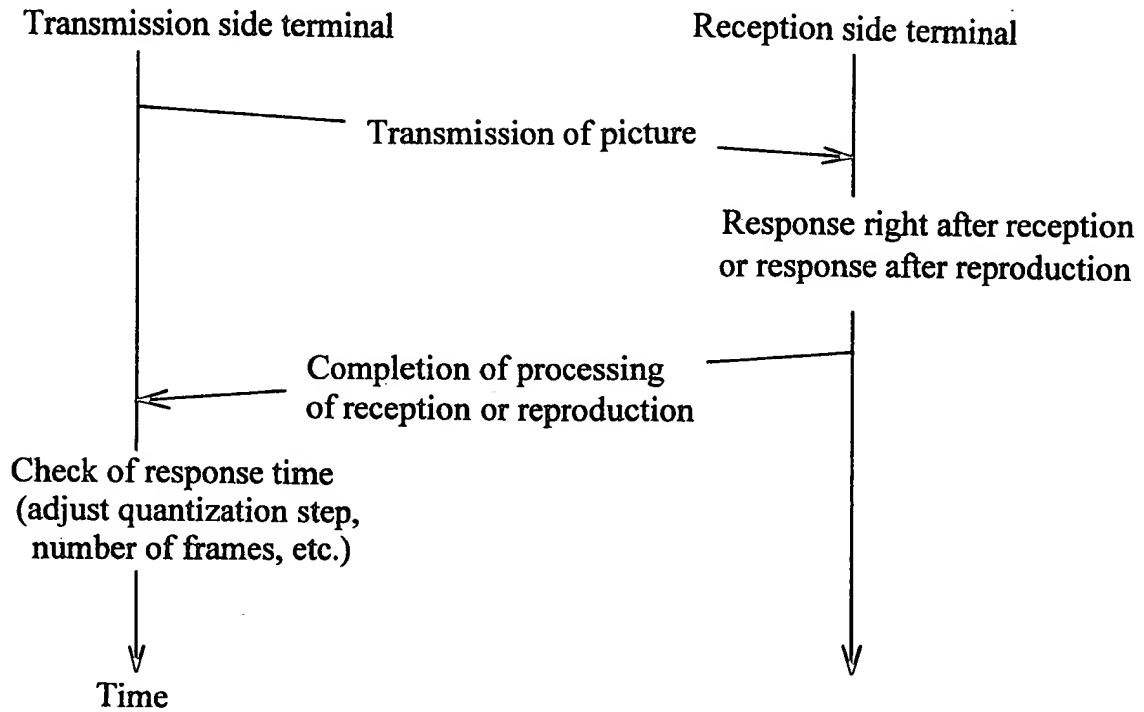


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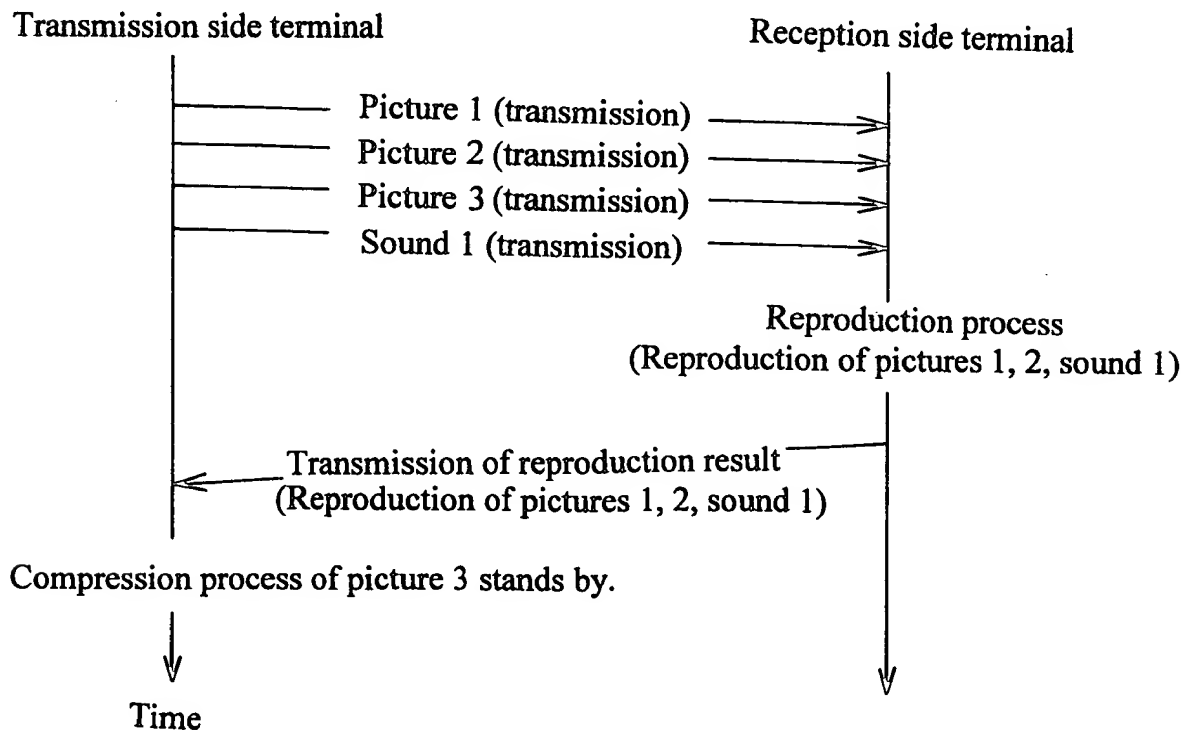
Fig. 16

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- Feedback relating to response between transmission terminal and reception terminal (case 1)



- Feedback of reproduction situation to transmission side terminal (case 2)



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